

Implementation of subgrid approaches accounting for unresolved topography in MPAS-Ocean

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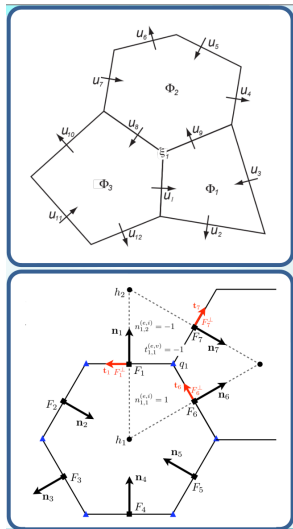
³ Los Alamos National Laboratory, NM, USA

E3SM Webminar, May 8, 2025

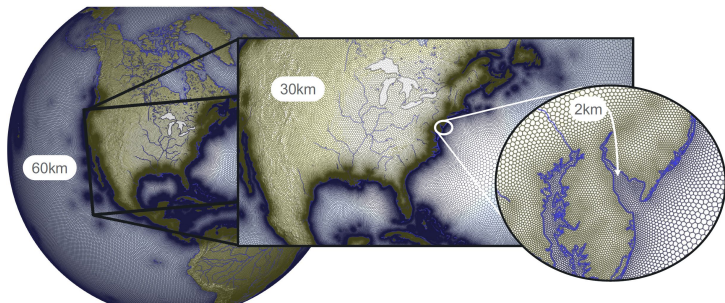


Model for Prediction Across Scales-Ocean (MPAS-Ocean) ¹

- Unstructured-grid ocean model
- Incompressible NS with the Boussinesq and hydrostatic approximation
- *Vertical*: ALE, z , z -star, σ coordinates
- *Method*: Finite Volume schemes
 - Maintains geostrophic balance.
 - Conserves energy
 - Maintain Lagrangian conservation of potential vorticity
- *Horizontal*: Voronoi tessellation, C-grid
- *Time stepping*: 2D barotropic/3D baroclinic mode splitting, RK4



¹Ringler, Thuburn, Klemp, Skamarock, JCP, 2010; Petersen et al, Ocean Modelling, 2015

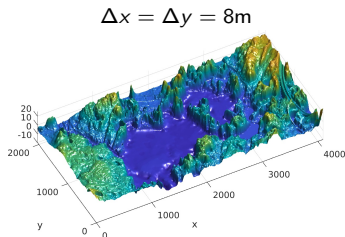
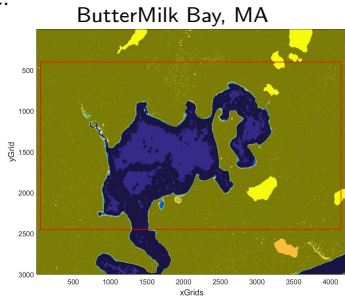


- Currently, MAPS-O global ocean component of E3SM resolves the ocean and its coast no finer than 6 km^2 .
- Resolution in the coastal zones will not be finer 2 km in the foreseeable future.
- Potentially insufficient to capture the hydrodynamics of the terrestrial-aquatic interface connecting the upland hydrology and the ocean through the hydraulic conveyances penetrating the coastal floodplain.

²Petersen et al., J. Adv. Model. Earth Syst., 2019

Subgrid modelling with unresolved topography

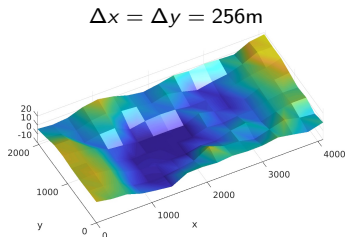
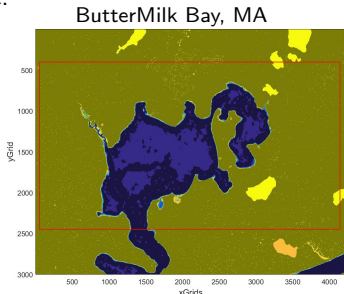
- The bottom profile is typically approximated on the *grid level*.
- A large amount of topographical detail could be lost in the low resolution case.



³ see Casulli, IJNMF, 2009; Stelling, Water Manag, 2012; Kennedy et al., Ocean Modelling, 2019

Subgrid modelling with unresolved topography

- The bottom profile is typically approximated on the *grid level*.
- A large amount of topographical detail could be lost in the low resolution case.



- Subgrid approaches³, which permit the use the subgrid bathymetric details, have been shown to be very effective in improving a coarse-grid model accuracy.

³ see Casulli, IJNMF, 2009; Stelling, Water Manag, 2012; Kennedy et al., Ocean Modelling, 2019

Implementation of subgrid correction

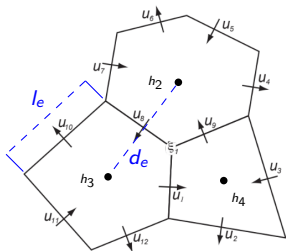
- A single-layer mode of MPAS-O:

$$\frac{\partial h}{\partial t} + \nabla \cdot (h\mathbf{u}) = 0.$$

$$\frac{\partial \mathbf{u}}{\partial t} + q\mathbf{u}^\perp = -\nabla g (\eta + K) - \frac{C_f}{h} |\mathbf{u}| \mathbf{u} + \frac{1}{h} \mathbf{F},$$

where $q = \mathbf{k} \cdot \nabla \times \mathbf{u} + f$, $\mathbf{u}^\perp = \mathbf{k} \times \mathbf{u}$, $K = |\mathbf{u}^2|/2$, $\eta = h - b$

- MPAS-O semi-discrete discretization on polygonal orthogonal C-grid.



$$\frac{d h_i}{dt} = -\frac{1}{A_i} \sum_{e \in EC(i)} u_{n,e} h_e l_e$$

$$\frac{d u_{n,e}}{dt} = \frac{g}{d_e} \sum_{i \in CE(e)} -n_{e,i} \eta_i - \frac{C_f}{\bar{h}_e} |\mathbf{u}_e| u_{n,e} + \frac{1}{\bar{h}_e} F_{n,e} + \text{TRiSK_adv_scheme} + \dots$$

Implementation of subgrid correction⁴

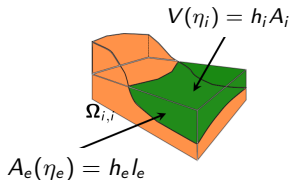
- In MPAS-O, as usual,

$$h_i = \eta_i + b_i, \quad b_i = \frac{1}{A_i} \int_{A_i} b(\mathbf{x}) d\mathbf{x}$$

- To correct mass,

$$h_i(\eta_i) = \frac{1}{A_i} \int_{A_i} \max(\eta_i + b(\mathbf{x}), 0) d\mathbf{x}$$

$$h_e(\eta_e) = \frac{1}{l_e} \int_{l_e} \max(\eta_e + b(\mathbf{x}), 0) d\mathbf{x}$$



- Assume constant friction slope flow,

$$C_f = \frac{1}{A_i} \frac{\left[\int_{A_i} \max(0, \eta_i + b(\mathbf{x})) d\mathbf{x} \right]^3}{\left[\int_{A_i} \max(0, \eta_i + b(\mathbf{x}))^{\frac{3}{2}} \sqrt{1/c_f} d\mathbf{x} \right]^2}$$

This 'bulk' C_f is well-suited for channel-like flow.

⁴Kennedy et al, Ocean modelling, 2019; Casulli, IJNFM, 2009

Parabolic bowl problem [Thacker, 1981]

- Frictionless rotating basin:

$$b(x, y) = h_0 \left(1 - \frac{r^2}{L^2} \right)$$

where $r = \sqrt{x^2 + y^2}$, $L = \text{Const.}$

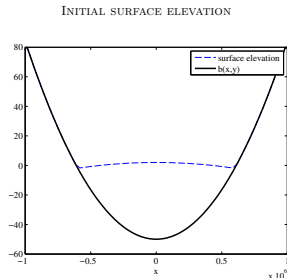
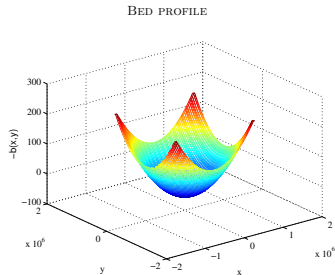
- Initial condition:

$$\mathbf{u}(\mathbf{x}, 0) = \frac{1}{2C_0} \left[f(\sqrt{1 - C^2} - C_0) \right] (-y, x)$$

$$H(\mathbf{x}, 0) = h_0 \left[\frac{\sqrt{1 - C^2}}{C_0} - \frac{r^2}{L^2} \left(\frac{1 + C}{C_0} \right) \right]$$

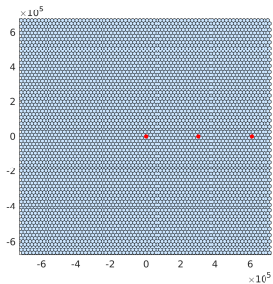
$$\eta(\mathbf{x}, 0) = H(\mathbf{x}, 0) - b(\mathbf{x})$$

- $C = \frac{(h_0 + \zeta_0)^2 - h_0^2}{(h_0 + \zeta_0)^2 + h_0^2}$, $\zeta_0 = \eta(\mathbf{0}, 0)$,
 $C_0 = 1 - C$
- $L = \sqrt{\frac{8gh_0}{\omega^2 - f^2}}$ for a given ω



Parabolic bowl problem

$h \sim 20\text{km}$



PARAMETERS:

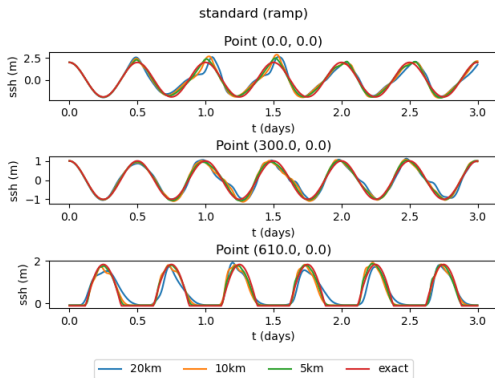
$$h_0 = 50\text{m}, \zeta_0 = 2\text{m},$$

$$f = 1.03 \times 10^{-3}, \omega = 2\pi/12 \text{ (hr}^{-1}\text{)}$$

NUMERICAL DETAILS:

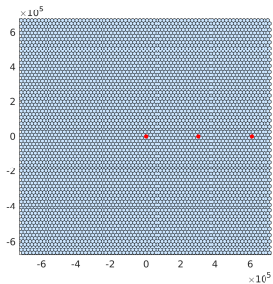
- $h = 20\text{ km}$ ($\Delta t = 200\text{s}$), 10 km ($\Delta t = 100\text{s}$), and 5km ($\Delta t = 50$).
- Subgrid bathy $h_s \sim 0.5/\sqrt{3}\text{ km}$.

TIME SERIES: STANDARD

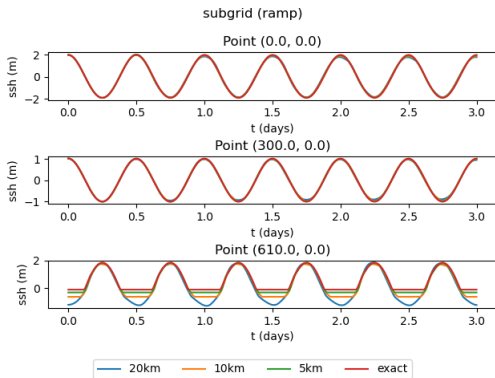


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TIME SERIES: SUBGRID



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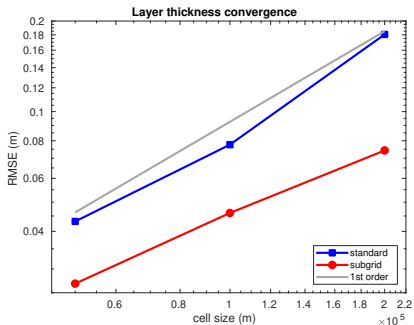
$f = 1.03 \times 10^{-3}$, $\omega = 2\pi/12$ (hr^{-1})

NUMERICAL DETAILS:

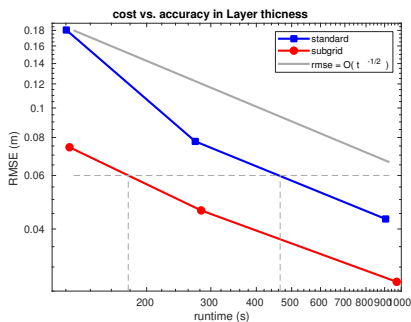
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Parabolic bowl problem

cell size vs. error



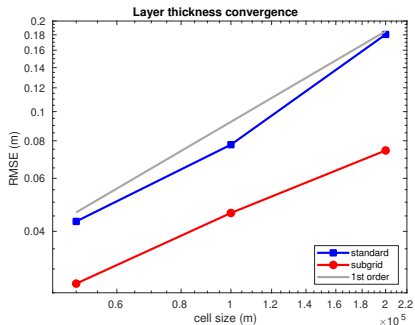
runtime vs. error



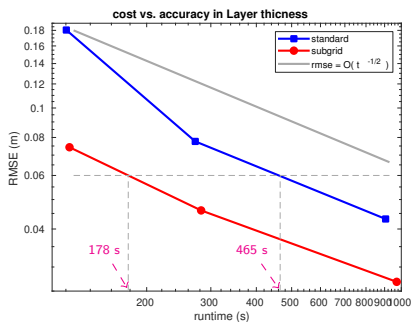
$$\bullet \text{ Error} = \sqrt{\frac{1}{N} \sum_i (H_{h,i} - H_{ex,i})^2}$$

Parabolic bowl problem

cell size vs. error

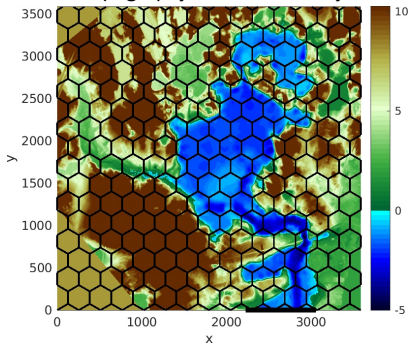


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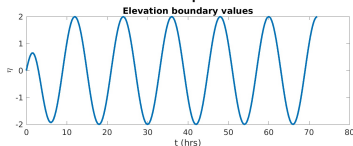


$$\bullet \text{ Error} = \sqrt{\frac{1}{N} \sum_i (H_{h,i} - H_{ex,i})^2}$$

LiDAR topography: Buttermilk bay, MA



Surface elevation imposed on the inlet



Problem:

- Flow is driven by elevation boundary
- Chezy coefficient = 0.017

Numerical method:

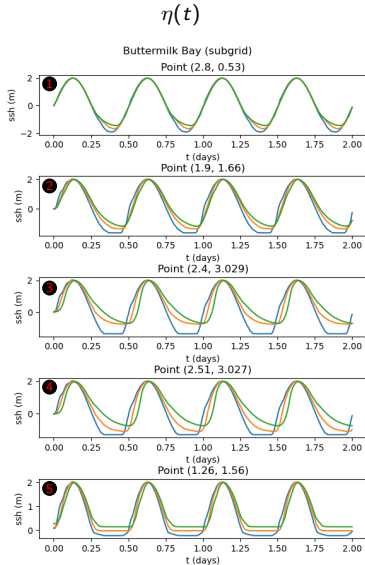
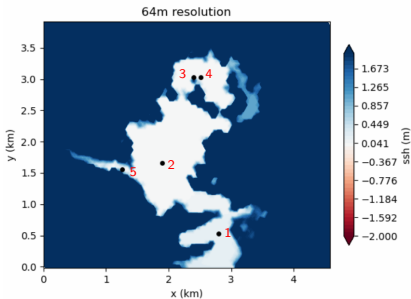
- RK4. $\Delta t = 10s$.
- Single layer.
- Uniform meshes:
 $h \sim 256m-64m$.
- Subgrid bathy $h_s \sim 6.4/\sqrt{3} m$

Buttermilk bay: standard

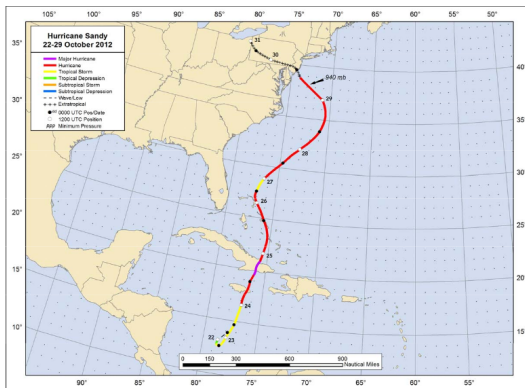
Buttermilk bay: subgrid

Buttermilk bay: time series

STATION LOCATIONS



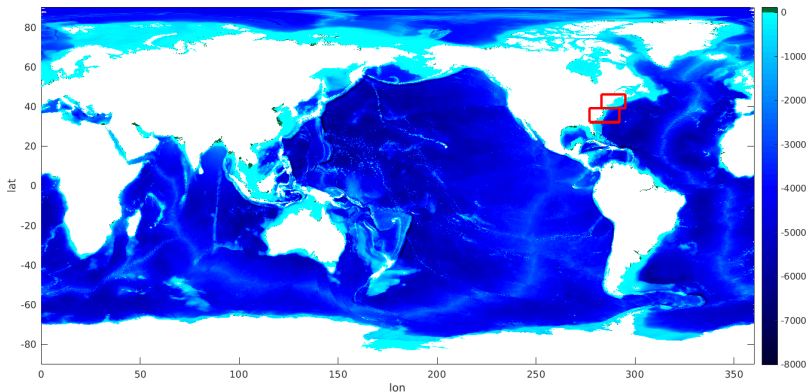
Storm Tide: Hurricane Sandy (2012)



source: <https://www.weather.gov/okx/hurricanesandy5year>

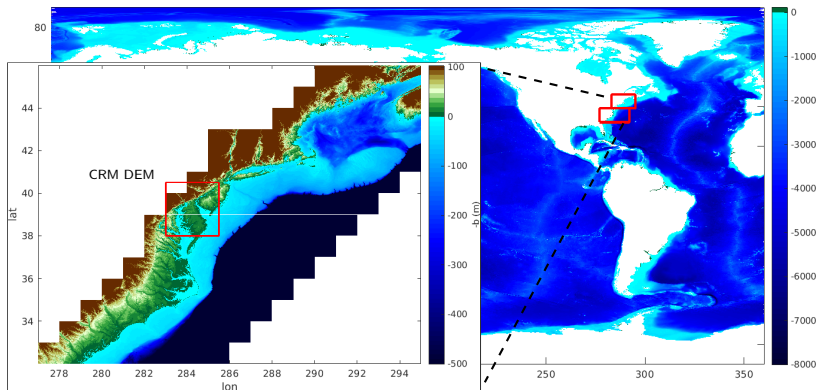
- SO12to60 mesh: 2.7×10^6 cells, 8.24×10^6 edges.
- Subgrid inset from SC to ME with CRM DEM ($\approx 30\text{m}$ res).
- Tides, wind stress and atm pressure (CFSv2), log law for bottom drag.
- $\Delta t = 5$ seconds. Run period 10/10/2012–11/02/2012.

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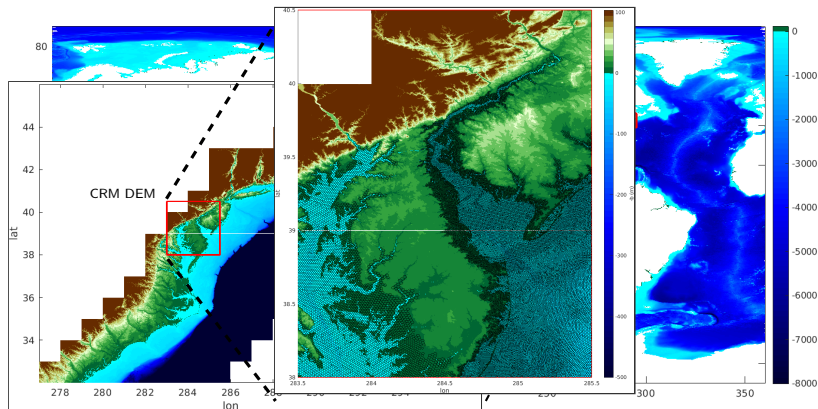
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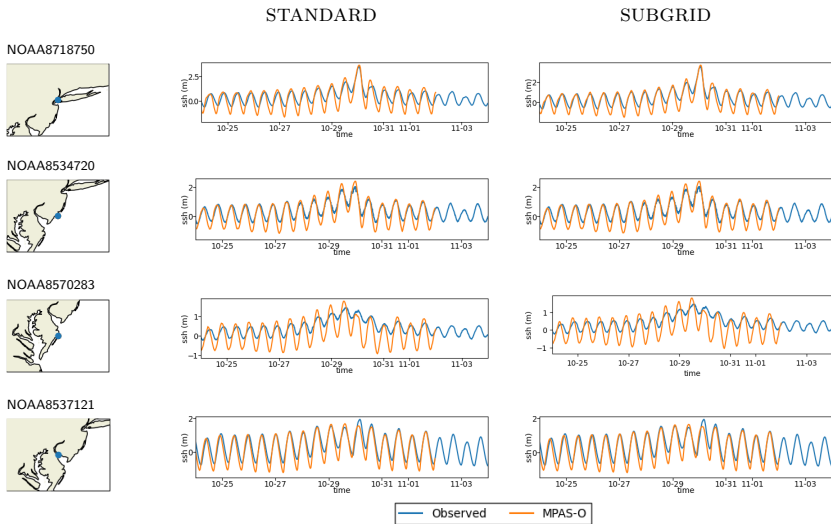
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Hurricane Sandy: SSH over NY coast, subgrid run

Hurricane Sandy: SSH validation, “open water” gauges

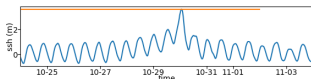


Hurricane Sandy. SSH validation, “coastal” gauges

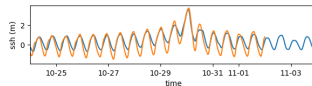
NOAA8557383



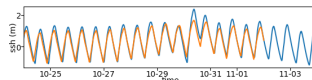
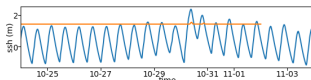
STANDARD



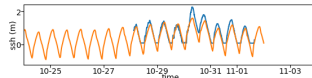
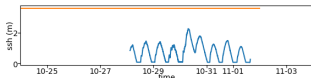
SUBGRID



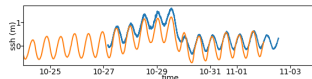
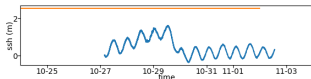
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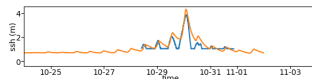
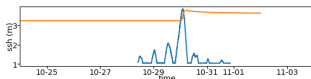
USGS-PA-PHI-014WL



USGS-VA-HAM-002WL



USGS-NJ-UNI-002WL



— Observed — MPAS-O

Summary

- The subgrid corrections using high resolution bathymetric and bed roughness data are implemented in the single-layer mode of the MPAS-Ocean.
- Verification and validation using idealized non-trivial test case with analytical solution clearly and real world applications show increased accuracy and gain cost-per-accuracy of the subgrid MPAS-Ocean solution.
- Simulations of global storm-tide with comprehensive forcing terms, including tides, self attraction and loading, internal tide parameterization, winds, and ice cap are underway!
- Although can be mitigated to some level by an unstructured grid, connectivity issues remain one of the most challenging aspects of the subgrid methods.

